

APPARATUS AND METHOD OF MAKING A REDUCED SENSITIVITY SPIN
VALVE SENSOR APPARATUS IN WHICH A FLUX INJECTION
EFFICIENCY IS REDUCED

RELATED APPLICATIONS

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10 The present application is related to commonly
assigned and copending U.S. Patent Application _____
(Attorney Docket No. 00-113-TAP) entitled "REDUCED
SENSITIVITY SPIN VALVE HEAD FOR MAGNETIC TAPE
APPLICATIONS," U.S. Patent Application _____ (Attorney
Docket No. 2001-019-TAP) entitled "APPARATUS AND METHOD
OF MAKING A REDUCED SENSITIVITY SPIN VALVE SENSOR
APPARATUS IN WHICH A BASIC MAGNETIC SENSITIVITY IS
15 REDUCED," and U.S. Patent Application _____ (Attorney
Docket No. 2001-020-TAP) entitled "APPARATUS AND METHOD
OF MAKING A REDUCED SENSITIVITY SPIN VALVE SENSOR
APPARATUS IN WHICH A FLUX CARRYING CAPACITY IS
INCREASED," all of which are filed on even date herewith
20 and are hereby incorporated by reference.

BACKGROUND OF THE INVENTION

1. Technical Field:

25 The present invention is directed to a reduced
sensitivity spin valve head for magnetic tape
applications.

2. Description of Related Art:

The requirement of high density magnetic storage of data on hard disk drives has been increasing steadily for the past several years. Hard disk drives include
5 magnetic heads for reading and writing data to the hard disk. The magnetic heads include write coils and sensors for reading data from the disks.

Development of magnetoresistive (MR) sensors (also referred to as heads) for disk drives in the early 1990's
10 allowed disk drive products to maximize storage capacity with a minimum number of components (heads and disks). Fewer components result in lower storage costs, higher reliability, and lower power requirements for the hard disk drives.

15 MR sensors are used for the read element of a read/write head on a high-density magnetic disk. MR sensors read magnetically encoded information from the magnetic medium of the disk by detecting magnetic flux stored in the magnetic medium of the disk. As storage
20 capacity of disk drives has increased, the storage bit has become smaller and its magnetic field has correspondingly become weaker. MR heads are more sensitive to weaker magnetic fields than are the inductive read coils used in earlier disk drives. Thus,
25 there has been a move away from inductive read coils to MR sensors for use in disk drives.

During operation of the hard disk drive, sense current is passed through the MR element of the sensor causing a voltage drop. The magnitude of the voltage
30 drop is a function of the resistance of the MR element.

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Docket No. 2001-021-TAP

Resistance of the MR element varies in the presence of a magnetic field. Therefore, as the magnitude of the magnetic field flux passing through the MR element varies, the voltage across the MR element also varies.

5 Differences in the magnitude of the magnetic flux entering the MR sensor can be detected by monitoring the voltage across the MR element.

As discussed above, MR sensors are known to be useful in reading data with a sensitivity exceeding that
10 of inductive or other thin film sensors. However, the development of Giant Magnetoresistive (GMR) sensors (also referred to as GMR head chips or Spin Valve sensors) has greatly increased the sensitivity and the ability to read densely packed data. Thus, although the storage density
15 for MR disks is expected to eventually reach 5 gigabits per square inch of surface disk drive (Gbits/sq.in.), the storage density of GMR disks is expected to exceed 100 Gbits/sq.in.

While GMR sensors, also known as Spin Valve sensors,
20 have increased the sensitivity of read heads of disk drives thereby allowing for advances in the recording density in magnetic disk recording technologies, it would be beneficial to be able to apply the spin valve sensors to other magnetic media, such as magnetic tape media.
25 However, the differences in performance of recording on magnetic tape and recording on magnetic disk media prevent the simple application of spin valve sensors to magnetic tape media.

Information is written onto a magnetic tape by
30 magnetizing tape regions. These magnetized tape regions

2001-021-TAP

produce a magnetic field, which can be detected and converted into an electrical signal by a read head.

Generally, a variety of different signal flux levels, i.e. levels of the magnetic field generated by the magnetic tape media, can be produce from various data patterns recorded on a magnetic tape. For example, low density patterns present a larger magnetic flux to the spin valve sensor leading to higher signal amplitude than high density patterns which have a lower level of magnetic flux. A spin valve head is typically designed and optimized to read the high density patterns in order to have significant amplitude for signal detection. However, the high input flux from a low density pattern can drive a spin valve sensor designed for high density operation into non-linear portions of the spin valve response curve. This leads to readback distortions and may even cause the spin valve sensor to magnetically saturate.

Write equalization, a method of breaking up the low
20 density signal with high density pulses, is often
employed to provide some equalization of the signal flux
as detected by the spin valve sensor. Unfortunately, due
to the increased complexity and cost of implementation,
write equalization has not been universally applied in
25 tape recording. Further, the problem of distortion when
reading low density waveforms is accentuated in systems
where downward read compatibility is required. In such
situations the range of recording densities seen by the
head can be extreme. Standard read head designs are not
30 capable of producing a sufficient readback amplitude at

Docket No. 2001-021-TAP

the high recording densities without high readback distortion at the lower densities.

Thus, it would be beneficial to have a reduced sensitivity spin valve head for magnetic tape applications in which much of the benefits of standard spin valve sensors are maintained while compensating for excessive input flux that may overpower the spin valve sensor.

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SUMMARY OF THE INVENTION

5 The present invention provides a reduced sensitivity
spin valve head for magnetic tape applications. The
present invention compromises a portion of the large
output gain derived from using state of the art spin
valve sensors in order to reduce the flux capture and
10 thus, the signal distortion in the spin valve sensor. In
order to provide a reduced sensitivity spin valve sensor,
one or more of the basic sensitivity of the spin valve,
the flux carrying capability of a free layer, and a flux
injection efficiency of the spin valve head structure are
15 modified to reduce the flux capture by the sensing layer.

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BRIEF DESCRIPTION OF THE DRAWINGS

5 The novel features believed characteristic of the invention are set forth in the appended claims. The invention itself, however, as well as a preferred mode of use, further objectives and advantages thereof, will best be understood by reference to the following detailed
10 description of an illustrative embodiment when read in conjunction with the accompanying drawings, wherein:

Figure 1 depicts a block diagram of a data recording system in which the present invention may be implemented;

Figure 2A and **2B** are exemplary block diagrams
15 illustrating a spin valve sensor in a magnetic read/write head in accordance with embodiments of the present invention;

Figures 3 and 4 are exemplary diagrams of layer configurations that may comprise a spin valve sensor in
20 accordance with the present invention;

Figure 5A is an exemplary diagram illustrating the manner by which the pinned and free layers of a spin valve sensor operate in the presence of an applied field;

Figure 5B is a diagram illustrating saturation of a
25 spin valve sensor;

Figure 6 is an exemplary diagram illustrating spin valve sensor saturation;

Figure 7 is an exemplary diagram illustrating the effects of increasing the field required to saturate the
30 spin valve sensor;

2001-021-TAP

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Figure 11 is an exemplary diagram of spin valve sensor read head in which two spin valve sensors are utilized.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

5 With reference now to the figures, and in particular with reference to **Figure 1**, a block diagram of a data tape recording system in which the present invention may be implemented is illustrated. Data recording system **100** is an example of a tape recording system that can record
10 data from a host computer onto magnetic tape. User data **110** enters the system to be written to magnetic tape media. The data is formatted and encoded **120**, passed through a write equalizer circuit **130** (if necessary), and fed to the writing head **150** by means of a write driver
15 **140** which supplies the electric current signals required for recording on the magnetic tape medium **105**.

When reading the recorded data from the magnetic tape medium **105**, the magnetic tape medium **105** is passed by a read head **170** in which the present invention may be
20 implemented, as discussed hereafter. The read head **170** transforms the magnetic flux emanating from the magnetic tape medium into electric voltage signals by means of the magnetoresistive effect. These voltages are amplified **180** and amplitude equalized **190** before being passed into
25 a detector **192** that interprets the signals as digital data. The data is un-encoded **195** and the user data **196** restored to the host computer.

Figures 2A and 2B show cross sections of a magnetic head **200** having a giant magnetoresistive (GMR) sensor or
30 spin valve sensor **210**. As shown in **Figure 2A**, the

T06230" B2E4660

Docket No. 2001-021-TAP

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magnetic head 200 includes an adjacent write head yoke 205, a spin valve sensor 210, coils 215, layered dielectrics 220, and magnetic shields 225. The magnetic head 200 is positioned above but in contact with a magnetic tape media 230. A gap between the magnetic head 200 and the magnetic tape media 230 is shown in Figure 2A for clarity only. The coils 215 generate a magnetic field for writing data to the magnetic tape media 230. The coils 215 are wrapped around yoke 205 which focuses the magnetic field created by the coils 215. The spin valve sensor 210 is used for reading data from the magnetic tape media 230. The layered dielectrics 220 are used as an insulator for insulating the spin valve sensor 210 from the magnetic shields 225. The magnetic shields 225 shield the spin valve sensor from upstream and downstream bits during the read operation.

Figure 2B shows a magnified view of a yoke style spin valve read head. The read head 219 includes a magnetoresistive spin valve element 210, i.e. spin valve sensor 210, positioned between two layers of an overcoat insulating material 240 and 245. The magnetoresistive spin valve element 210 is in close proximity to a top flux guide 250. The top flux guide 250 is separated from a bottom flux guide 255 by a gap insulator 260, planars 270, and bias conductor 280.

When the magnetoresistive (MR) spin valve element 210 is formed, a magnetic field is typically applied in a direction parallel to the plane of the spin valve element 210. Thus, the MR spin valve element 210 exhibits a uniaxial anisotropy with an easy-axis of magnetization

parallel to the direction of the applied field. As a magnetic tape media passes the spin valve read head, an external magnetic field is conducted by the top flux guide 250 and the bottom flux guide 255 to generate a magnetic field that is applied normal to the easy-axis of the MR spin valve sensing layer element 210. The gap insulator 260, planars 270 and bias conductor 280 aid in conducting the magnetic flux from the magnetic tape media so that it is applied normal to the easy axis of the MR spin valve sensing layer element 210.

The spin valve sensor in these head structures is briefly described as follows. Referring to **Figures 3 and 4**, the spin valve is a layered structure based on two ferromagnetic layers 310 and 320 (for example, NiFe or CoFe) separated by a thin non-magnetic layer 330 (e.g., copper). One of the ferromagnetic layers 310 has its magnetization pinned, i.e. fixed, at 90 degrees with respect to the other ferromagnetic layer's 320 longitudinal oriented easy axis. This is called the pinned layer 310 and is held in place by the exchange field from an adjacent antiferromagnet 340 (such as NiO, PtMn or NiMn). The second ferromagnetic layer 320 has its magnetization free to rotate for sensing applied magnetic fields and is called the free or sensing layer.

Figures 3 and 4 are two embodiments of spin valves with different types of antiferromagnet/ferromagnet arrangements to achieve the same end. A diagram of the magnetic situation is shown in **Figure 5A**. In response to an external magnetic field H_{applied} being applied normal to the easy axis of the spin valve element free layer, the

magnetization direction of the free layer rotates away from the easy axis direction toward the direction of the applied field. This magnetization rotation causes the electrical resistance of the spin valve element to
5 change. Based on changes in the resistance of the MR spin valve element and thus, the voltage output seen in the presence of a sense current i , the data recording on the magnetic tape can be read.

Saturation of the sensing layer of the spin valve
10 occurs when the magnetization cannot rotate further. Once the layers magnetization is fully parallel to the applied field, the resistance ceases to change with further increases in applied magnetic field. **Figure 5B** demonstrates this relationship between the applied field
15 and the change in resistance.

The present invention provides apparatus for reducing the sensitivity of a conventional spin valve sensor so that it may be used with magnetic tape media without causing saturation of the spin valve sensor. In
20 this way, the induced signal distortion that would occur if a conventional spin valve sensor were used with magnetic tape media is avoided.

Figure 6 is an exemplary diagram illustrating the components used to calculate spin valve saturation. As
25 shown in **Figure 6**, the input flux from magnetic tape media 610 that is sensed by the spin valve sensor 620 is represented as $4\pi M_r \delta W$ where M_r is the remnant magnetic moment, i.e. the magnetic moment of the magnetized region on the tape once the magnetizing field has been removed
30 after the writing process, δ is the thickness of the

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Docket No. 2001-021-TAP

magnetic tape media, W is the width of the magnetic tape media, and 4π is a constant. Since the flux that is sensed by the spin valve sensor 620 is obtained from both opposing regions of magnetized tape media passing in front of the spin valve sensor, the total input flux is $8\pi M_r \delta W$.

Thus, the saturation flux density of a spin valve can be defined as the quantity of the input flux multiplied by the flux injection efficiency, divided by the quantity of the thickness of the free layer of the spin valve sensor multiplied by the width of the magnetic tape media. The free layer is a thin film layer of the spin valve sensor whose magnetization direction is free to rotate in response to an applied field. In mathematical form, this relationship is defined as:

$$B_s = (8\pi * M_r * \delta * \xi) / t \quad (1)$$

where B_s is the saturation flux density, M_r is the remnant magnetic moment, δ is the thickness of the magnetic tape media, and ξ is the flux injection efficiency. The flux injection efficiency is the ratio of the flux that actually enters the spin valve to the total amount of flux available leaving the magnetic tape media. In this format, the widths of the magnetic tape media in the numerator and denominator mathematically cancel.

From this relationship, it can be seen that in order to adjust the saturation flux density, and thus, the sensitivity of the spin valve sensor read head, there are

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Docket No. 2001-021-TAP

two different quantities that may be modified. The first quantity that may be modified is the flux carrying capability of the spin valve sensor. This may entail changing the value of t , the thickness of the free layer, or sensing layer, of the spin valve sensor.

Alternatively, this may entail changing the value of the input flux, $8\pi M_r \delta W$. The second quantity that may be modified is the flux injection efficiency, ξ . As will be described in greater detail hereafter, there are a number of different ways in which the values for these quantities may be modified through various configurations of the spin valve sensor read head.

The sensitivity of the spin valve read head may be modified in yet another manner. The output of the spin valve read head itself may be modified, i.e. the sensitivity of the spin valve read head may be modified directly. Consider the voltage output of the spin valve read head which is defined as:

$$dV = (I_b R_0 (dR/R) dH) / 2H_k \quad (2)$$

where dV is the output voltage, I_b is the spin valve sensor current, R_0 is the resistance of the spin valve sensor element, dR/R is a change in the resistance of the spin valve sensor element, H_k is the anisotropy field value, i.e. the strength of the field required to swing the magnetization direction from an easy-axis to a hard-axis, and dH is the change in the magnetic field. The anisotropy field value is also a measure of the strength of the field required to saturate the spin valve sensor.

2001-021-TAP

From this relationship, it can be seen that by increasing the value for H_k , the output of the spin valve sensor may be decreased and thus, the sensitivity of the spin valve sensor may be decreased. The present invention provides spin valve sensor configurations which may be used to increase the magnetic field required to saturate the spin valve sensor, as discussed in greater detail hereafter.

One way in which to increase the value for H_k is to increase the stiffness of the spin valve sensor. This is shown in **Figure 7**. As shown in **Figure 7**, a first curve 710 represents an output from a standard spin valve sensor. The second curve 720 represents the output from a spin valve sensor that has been stiffened in accordance with the present invention, as described hereafter. By stiffening the spin valve sensor, for the same magnetic field, the output of the spin valve sensor is lower. Thus, the amount of the magnetic field needed to saturate the spin valve sensor, i.e. the anisotropy field, is increased. For example, as shown in **Figure 7**, the magnetic field required to saturate the standard spin valve sensor is approximately 200 oersteds (Oe), while for the stiffened spin valve sensor, the magnetic field required to saturate the sensor is approximately 400 Oe.

Thus, the present invention, as described hereafter, provides reduced sensitivity spin valve sensor read heads in which one or more of the flux carrying capability of the spin valve sensor, the flux injection efficiency of the spin valve sensor, and the basic magnetic sensitivity of the spin valve sensor are modified from that of a standard spin valve sensor. In this way, a spin valve

Docket No. 2001-021-TAP

sensor is provided that has reduced sensitivity such that the readback distortion in the spin valve sensor is reduced and the field required to saturate the spin valve sensor is increased.

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REDUCING THE BASIC MAGNETIC SENSITIVITY

As mentioned above, one way in which to reduce the sensitivity of a conventional spin valve sensor is to magnetically increase the stiffness of the free layer, or sensing layer, of the spin valve sensor. One way to increase the stiffness of the free layer of the spin valve sensor is to increase the effective anisotropy field H_k . **Figure 8** is an exemplary block diagram illustrating one embodiment of the present invention in which permanent magnet stabilizing elements are used to increase the stiffness of the free layer of the spin valve sensor.

As shown in **Figure 8**, the spin valve sensor **810** is positioned between two films **820** and **830** of insulating material such as alumina, silicon nitride, aluminum nitride, or the like, a top magnetic shield **840** and bottom magnetic shield **850**. The insulating films **820**, **830** provide insulation and spacing for the spin valve sensor **810** from the top and bottom magnetic shields **840** and **850**.

The spin valve sensor **810** is stiffened by permanent magnet stabilizing elements **860** and **870**. When magnetized in a longitudinal direction parallel to the free layer easy axis, the permanent magnetic stabilizing elements

Docket No. 2001-021-TAP

860 and 870 apply a longitudinal field to the spin valve free layer. This additional field effectively magnetically "stiffens" the free layer. By stiffening the free layer of the spin valve sensor 810, what is
5 meant is that the amount of magnetic field required to cause the magnetization direction of the free layer of the spin valve sensor to rotate away from the easy-axis is increased and the sensors propensity to saturate is reduced. As a result, the voltage output of the spin
10 valve sensor 810 is reduced.

In a preferred embodiment, the permanent magnet stabilizing elements 860 and 870 are cobalt-platinum/chromium magnets. Cobalt-platinum/chromium magnets are chosen for the preferred embodiment because
15 they have good permanent magnetic properties with in-plane anisotropy to ensure the applied field is in the desired direction.

In alternative embodiments, the same effect of stiffening the free layer of the spin valve sensor may be
20 obtained by introducing an antiferromagnet into the spin valve sensor configuration. These alternative embodiments are shown in **Figures 9**. As shown in **Figure 9A**, an antiferromagnetic layer 910 is placed in close proximity, such as an overlay, to the free layer of the
25 spin valve sensor 920. The free layer of the spin valve sensor is a ferromagnetic layer and tends to have adjacent flux guide moments line up in the same direction. Thus, the free layer moment of the spin valve sensor 920 is aligned with the magnetic exchange field
30 derived from the antiferromagnet.

2001-021-TAP

The antiferromagnet layer 910 tends to have the moments of adjacent atoms point in opposite directions. Thus, there is no net macroscopic moment in the antiferromagnetic layer 910. It is known that if a
5 ferromagnetic layer is in contact with an antiferromagnetic layer, the moments of atoms in the ferromagnetic layer at the interface with the antiferromagnetic layer will be aligned with the moments of atoms at the corresponding interface of the
10 antiferromagnetic layer. This effect is known as exchange bias or exchange anisotropy.

In view of the above, under appropriate conditions, substantially all of the atomic moments in the free layer of the spin valve sensor 920, i.e. the ferromagnetic
15 layer, can be aligned in a desired direction due to adjacent antiferromagnetic layer 910. Once aligned, a longitudinal exchange induced bias field is introduced into the free layer of the spin valve sensor 920. This longitudinal exchange induced bias field stiffens the
20 free layer of the spin valve sensor 920 in much the same manner as with the magnetic stabilizing elements shown in Figure 8.

Figure 9B shows an alternative embodiment in which an additional ferromagnetic layer 970 is used which is
25 pinned with its magnetization parallel to the long axis of the free layer 950 by use of the 0 degree pinning antiferromagnet 980. The additional 0 degree pinning antiferromagnet 980 preferably has a different blocking temperature from the 90 degree pinning antiferromagnet so

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Docket No. 2001-021-TAP

that the two antiferromagnets can sequentially be annealed with their appropriate orientations.

The additional ferromagnetic layer 970 is spaced away from the free layer by a thin non-magnetic layer 960 (such as copper, gold, an electron reflecting oxide layer, or the like) thickness can be used to control the amount of ferromagnetic exchange between the 0 degree pinned layer 970 and free layer 950. The thickness of this layer, in a preferred embodiment, is approximately between 10 and 25 Angstroms depending on the strength of the effect desired. Thus, the use of the configuration in Figure 9B provides a "tunable" spin valve sensor.

27 The use of an antiferromagnetic layer in a magnetoresistive element is generally taught in commonly assigned and copending U.S. Patent Application Serial No. 09/170,330 (Attorney Docket No. 98-013-TAP) entitled "Dual Element Magnetoresistive Read Head with Integral Element Stabilization," filed on 10/13/98, and which is hereby incorporated by reference. In this application, an antiferromagnetic layer is used in a normal magnetoresistive read head for stabilizing a magnetic domain of the magnetoresistive read head. An undesirable consequence of using the antiferromagnetic layer in this application was the loss of sensitivity of the MR layer. The present invention recognizes the value of loss of sensitivity in this manner when applied to spin valve sensors for magnetic tape read heads, an advantage not recognized in this prior incorporated U.S. Patent Application Serial No. 09/170,330 (Attorney Docket No. 98-013-TAP).

09/170,330 "Dual Element Magnetoresistive Read Head with Integral Element Stabilization"

By using one or more of these approaches to stiffening the free layer of the spin valve sensor, the magnetic field required to saturate the spin valve sensor is increased. Thus, the sensitivity of the spin valve
5 sensor is reduced. As a result, the readback distortion in the sensed magnetic fields is greatly diminished.

INCREASING THE FLUX CARRYING CAPACITY

10 In addition to stiffening the spin valve sensor, the flux carrying capacity of the spin valve sensor may be increased in order to reduce the sensitivity of the spin valve sensor. One way to increase the flux carrying capacity is to increase the thickness of the free layer
15 of the spin valve sensor. Currently, the free layer of known spin valve sensors have thicknesses of between 30 and 60A. With the present invention, this thickness is increased to a value above 60A. In a preferred embodiment, the thickness of the free layer of the spin
20 valve sensor is approximately between 90 and 120A.

By increasing the thickness, and thus the cross sectional area, of the free layer of the spin valve sensor, its flux carrying capability is increased and the amount by which the free layer moment rotates for a given
25 flux input is decreased. Thus, the sensitivity of the spin valve sensor is decreased.

Another way in which the flux carrying capability of the spin valve sensor may be increased is to use a dual type spin valve sensor. Dual MR sensors and spin valve
30 sensors are generally known in the art. For example,

096433-05994

Docket No. 2001-021-TAP

commonly assigned and copending U.S. Patent Application
No. 09/078,155 (Attorney Docket No. 96-061-TAP) entitled
"Method for Reading Both High and Low Density Signals
with an MR Head," filed 5/13/98, which is incorporated
5 herein by reference, describes the use of a dual MR
sensor read head for reading high and low density
signals. In addition, U.S. Patent No. 5,287,238, issued
on February 15, 1994 to Baumgard et al. and entitled
"Dual Spin Valve Magnetoresistive sensor," and which is
10 hereby incorporated by reference, teaches a dual spin
valve MR sensor having first, second and third layers of
ferromagnetic material separated from each other by
layers of non-magnetic metallic material.

The dual spin valve MR sensor of Baumgard et al. is
15 depicted in **Figure 10A**. As shown in **Figure 10A**, the dual
spin valve MR sensor of Baumgard includes three layers of
ferromagnetic material 31, 35 and 39. The dual spin
valve MR sensor of Baumgard further includes two layers
of non-magnetic material 33 and 37. The magnetizations
20 of the two outer layers 31 and 39 of ferromagnetic
material are oriented parallel to each other, i.e., in
the same direction, and at an angle of about 90 degrees
with respect to the magnetization of the intermediate
layer 35 of ferromagnetic material in the absence of an
25 externally applied magnetic field as indicated by arrows
32, 34 and 38, respectively. In addition, the
magnetization directions of the first and third outer
layers, 31 and 39 of ferromagnetic material are fixed, or
pinned, in a preferred orientation as shown by the arrows
30 32 and 38. Thus, while the magnetization directions of

T06230" B4E4636D

the outer ferromagnetic layers 31, 39 remain fixed, the magnetization in the intermediate layer 35 of ferromagnetic material is free to rotate its direction in response to an externally applied magnetic field (such as magnetic field H), as shown by the dashed arrows 34 on layer 35. The dual spin valve MR sensor of Baumgard provides a large MR response at low applied magnetic fields. This is contrary to the desired result of the present invention.

Figure 10B illustrates a dual spin valve MR sensor according to one embodiment of the present invention. As shown in Figure 10B, the configuration is similar to that of the Baumgard dual spin valve MR sensor with the exception that four ferromagnetic material layers 1010-1040 are provided and spaced from one another by three non-magnetic spacers 1050-1070. The two outer ferromagnetic layers 1010 and 1040 are pinned, i.e. have fixed magnetization directions. The two inner ferromagnetic layers 1020 and 1030 are free layers whose magnetization directions are free to rotate based on an applied magnetic field. By providing two free layers, the present invention allows the magnetic flux to be spread across the two free layers thereby reducing the magnetic flux fed to each free layer to half. By reducing the magnetic flux in this manner, the saturation propensity is reduced (see equation (1)). In this case, the high output afforded by the spin valve sensor is retained as the electron scattering mechanism responsible for the GMR effect at layer interfaces is preserved without any shunting by thicker layers.

REDUCING THE FLUX INJECTION EFFICIENCY

As another mechanism for reducing the sensitivity of
5 the spin valve sensor, the flux injection efficiency, ξ ,
of the spin valve sensor head may be reduced. There are
a number of ways in which this may be accomplished.

One way in which to reduce the flux injection
efficiency is to reduce the space between the spin valve
10 sensor and the magnetic shields. This bleeds the flux to
the shields quicker and reduces the flux injection
efficiency. In order to reduce the space between the
spin valve sensor and the magnetic shields, the thickness
of the insulation layers between the spin valve sensor
15 and the magnetic shields may be reduced.

Yet another way in which the flux injection
efficiency may be reduced is to use an inefficient yoke
structure that feeds less flux into the spin valve
sensor. The efficiency of flux transfer from the
20 magnetic tape media through the flux guides can be
adjusted by altering the spacing between the flux guide
and the spin valve element or by altering the magnetic
properties of the flux guides. Such structures are
generally known, see Koel et al. "Thin film magnetic head
25 for reading and writing information," U.S. Patent No.
4,150,408, which is hereby incorporated by reference, but
in practice show relatively low output signals due to
this inefficiency. An embodiment of the present
invention similar to the structure of Koel et al. is
30 shown in **Figure 11**.

2001-021-TAP

As shown in **Figure 11**, the spin valve sensor read head is essentially the same as the prior art spin valve read head depicted in **Figure 2B** with the exception that a second spin valve element **1110** is provided on the planars **1120**. In this way, the flux generated by the top flux guide **1130** and the bottom flux guide **1140** is shared between both the first spin valve element **1150** and the second spin valve element **1160**. As a result the amount of flux handled by each spin valve element is reduced and thus, the flux injection efficiency of each spin valve element is reduced. This causes the saturation propensity to be reduced.

Each of these various mechanisms can be used alone or in conjunction with other ones of these mechanisms to reduce the sensitivity of the spin valve sensor read head. As mentioned above, the sensitivity is reduced in order to reduce the readback distortion in the signals generated by the spin valve sensor. However, the sensitivity of the spin valve sensor is not be reduced so much as to eliminate the benefits provided by spin valve sensors. Rather, a compromise of benefits is intended by the present invention.

The description of the present invention has been presented for purposes of illustration and description, and is not intended to be exhaustive or limited to the invention in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art. The embodiment was chosen and described in order to best explain the principles of the invention, the practical application, and to enable others of

Docket No. 2001-021-TAP

ordinary skill in the art to understand the invention for various embodiments with various modifications as are suited to the particular use contemplated.

2001-021-TAP